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# ESM-4930 96 x 48 1/8 DIN Universal Input PID Process Controller

- 4 digits process (PV) and 4 digits process set (SV) display
- Universal process input (TC, RTD, mV \_\_\_\_, V \_\_\_\_, mA \_\_\_\_)
- Dual or multi point calibration for \_\_\_\_Voltage / Current input
- Configurable ON/OFF, P, PI, PD ve PID control forms
- Adaptation of PID coefficients to the system with Auto-tune and Self-tune
- Manual/Automatic mode selection for control outputs
- Bumpless transfer
- Programmable heating, cooling and alarm functions for control outputs

# ABOUT INSTRUCTION MANUAL

Instruction manual of ESM-4930 process controller consists of two main sections. Explanation of these sections are below. Also, there are other sections which include order information and technical specifications of the device. All titles and page numbers in instruction manual are in "**CONTENTS**" section. User can reach to any title with section number.

#### Installation:

In this section, physical dimensions of the device, panel mounting, electrical wiring, physical and electrical installation of the device to the system are explained.

#### **Operation and Parameters:**

In this section, user interface of the device, how to access to the parameters, description of parameters are explained.

Also in these sections, there are warnings to prevent serious injury while doing the physical and electrical mounting or using the device.

Explanation of the symbols which are used in these sections are given below.



This symbol is used for safety warnings. User must pay attention to these warnings.



This symbol is used to determine the dangerous situations as a result of an electric shock. User must pay attention to these warnings definitely.



This symbol is used to determine the important notes about functions and usage of the device.

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# **EU DECLARATION OF CONFORMITY**

Manufacturer Company Name : Emko Elektronik A.S..

Manufacturer Company Address: DOSAB, Karanfil Sokak, No:6, 16369 Bursa, Turkiye

The manufacturer hereby declares that the product conforms to the following standards and conditions.

Product Name	: Process Controller
Model Number	: ESM-4930
Type Number	: ESM-4930
Product Category laboratory use	: Electrical equipment for measurement, control and

Conforms to the following directives :

2006 / 95 / EC The Low Voltage Directive

2004 / 108 / EC The Electromagnetic Compatibility Directive

## has been designed and manufactured to the following specifications :

EN 61000-6-4:2007	EMC Generic Emission Standard for the Industrial Environments
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EN 61000-6-2:2005 EMC Generic Immunity Standard for the Industrial Environments

EN 61010-1:2001 Safety Requirements for electrical equipment for measurement, control And laboratory use

When and Where Issued	Authorized Signature					
16 <sup>th</sup> October 2009	Name	: Serpil YAKIN				
Bursa-TURKEY	Position	: Quality Manager				

# 1.Preface

ESM series process controllers are designed for measuring and controlling temperature and any process value. They can be used in many applications with their universal process input, control outputs, selectable alarm functions.

Some application fields and an applications which they are used are below:

Application FieldsAGlassFPlasticPetro-ChemistryTextileAutomativeMachine production industries

Application PID Process Control

# **1.1 General Specifications**



# 1.2 Ordering Information

ESM-4930 (96x48 1/8 DIN)		Α	вс	D	E	1	FG	н	1	U	v	w	z	
COIVI-493U (96x48 1/8 DIN)				0	1	1	01	02	1					
A Supply Voltage														
1														
2	24 V~ (-15%;+10%) 50/60	Hz	24\	/	: (-1	5%;	+10	%)						
9	Customer (Maximum 240V-	~ (-	15%	;+1(	0%))	) 50/	'60H	z						
BC	Input Type			S	cal	е								
20	Configurable (Table-1)			Та	able	-1								
D Serial Communication														
		0 None												
0	None													(
0 E	None Output-1			_		_	_	_	_					
		at re	esist	ive l	load	)								
<b>E</b>	Output-1	at re	esist	ive	load	)								
<b>E</b>	Output-1 Relay Output (5A@250V~					,								
<b>E</b> 1 <b>FG</b> 01	Output-1 Relay Output (5A@250V~ Output-2					,								

#### Table-1

BC	Input Type(TC)	Scale(°C)	Scale(°F)
21	L ,Fe Const DIN43710	-100°C,850°C	-148°F ,1562°F
22	L ,Fe Const DIN43710	-100.0°C,850.0°C	-148.0°F,999.9°F
23	J ,Fe CuNi IEC584.1(ITS90)	-200°C,900°C	-328°F,1652°F
24	J ,Fe CuNi IEC584.1(ITS90)	-199.9°C,900.0°C	-199.9°F,999.9°F
25	K ,NiCr Ni IEC584.1(ITS90)	-200°C,1300°C	-328°F,2372°F
26	K ,NiCr Ni IEC584.1(ITS90)	-199.9°C,999.9°C	-199.9°F,999.9°F
27	R ,Pt13%Rh Pt IEC584.1(ITS90)	0°C,1700°C	32°F,3092°F
28	S ,Pt10%Rh Pt IEC584.1(ITS90)	0°C,1700°C	32°F,3092°F
29	T ,Cu CuNi IEC584.1(ITS90)	-200°C,400°C	-328°F,752°F
30	T ,Cu CuNi IEC584.1(ITS90)	-199.9°C,400.0°C	-199.9°F,752.0°F
31	B,Pt30%Rh Pt6%Rh IEC584.1(ITS90)	44°C,1800°C	111°F,3272°F
32	B,Pt30%Rh Pt6%Rh IEC584.1(ITS90)	44.0°C,999.9°C	111.0°F,999.9°F
33	E ,NiCr CuNi IEC584.1(ITS90)	-150°C,700°C	-238°F,1292°F
34	E ,NiCr CuNi IEC584.1(ITS90)	-150.0°C,700.0°C	-199.9°F,999.9°F
35	N,Nicrosil Nisil IEC584.1(ITS90)	-200°C,1300°C	-328°F,2372°F
36	N,Nicrosil Nisil IEC584.1(ITS90)	-199.9°C,999.9°C	-199.9°F,999.9°F
37	C , (ITS90)	0°C,2300°C	32°F,3261°F
38	C , (ITS90)	0.0°C,999.9°C	32.0°F,999.9°F
BC	Input Type(RTD)	Scale(°C)	Scale(°F)
39	PT 100, IEC751(ITS90)	-200°C,650°C	-328°F,1202°F
40	PT 100 , IEC751(ITS90)	-199.9°C,650.0°C	-199.9°F,999.9°F
BC	Input Type ( Voltage and C	Scale	
41	050 mV <del></del>	-1999, 9999	
42	05 V <del></del>	-1999, 9999	
43	010 V	-1999, 9999	
44	020 mA	-1999, 9999	
45	420 mA <del></del>	-1999, 9999	

All order information of ESM-4930 are given on the table at left. User may form appropriate device configuration from information and codes that at the table and convert it to the ordering codes.

Firstly, supply voltage then other specifications must be determined. Please fill the order code blanks according to your needs.

Please contact us, if your needs are out of the standards.

 $\begin{array}{c} & & \\ & & \\ \hline \end{array} \\ \hline \end{array} \\ \begin{array}{c} \sim \\ = \\ - \\ \end{array} \\ \begin{array}{c} \text{Symbol means Vac,} \\ \text{Symbol means Vac and Vdc} \\ \hline \end{array} \\ \end{array}$ 

# 1.3 Warranty

EMKO Elektronik warrants that the equipment delivered is free from defects in material and workmanship. This warranty is provided for a period of two years. The warranty period starts from the delivery date. This warranty is in force if duty and responsibilities which are determined in warranty document and instruction manual performs by the customer completely.

# 1.4 Maintenance

Repairs should only be performed by trained and specialized personnel. Cut power to the device before accessing internal parts.

Do not clean the case with hydrocarbon-based solvents (Petrol, Trichlorethylene etc.). Use of these solvents can reduce the mechanical reliability of the device. Use a cloth dampened in ethyl alcohol or water to clean the external plastic case.

## 2.Installation

Before beginning installation of this product, please read the instruction manual and warnings below carefully.

In package,

- One piece unit
- Two pieces mounting clamps
- One piece instruction manual

A visual inspection of this product for possible damage occured during shipment is recommended before installation. It is your responsibility to ensure that qualified mechanical and electrical technicians install this product.

If there is danger of serious accident resulting from a failure or defect in this unit, power off the system and separate the electrical connection of the device from the system.

The unit is normally supplied without a power switch or a fuse. Use power switch and fuse as required.

Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.

Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

Never attempt to disassemble, modify or repair this unit. Tampering with the unit may results in malfunction, electric shock or fire.

Do not use the unit in combustible or explosive gaseous atmospheres.

During the equipment is putted in hole on the metal panel while mechanical installation some metal burrs can cause injury on hands, you must be careful.

Montage of the product on a system must be done with it's fixing clamps. Do not do the montage of the device with inappropriate fixing clamp. Be sure that device will not fall while doing the montage.

It is your responsibility if this equipment is used in a manner not specified in this instruction manual.

## 2.1 General Description



# 2.2 Dimensions



Maximum 15mm / 0.59 inch



# 2.4 Environmental Ratings

#### **Operating Conditions**



**Operating Temperature** : 0 to 50 °C



Max. Operating Humidity: 90% Rh (non-condensing)



Altitude

: Up to 2000m.



Forbidden Conditions: Corrosive atmosphere Explosive atmosphere Home applications (The unit is only for industrial applications)

## 2.5 Panel Mounting



1-Before mounting the device in your panel, make sure that the cutout is of the right size.

2-Check front panel gasket position

3-Insert the device through the cut-out. If the mounting clamps are on the unit, put out them before inserting the unit to the panel.



During installation into a metal panel, care should be taken to avoid injury from metal burrs which might be present. The equipment can loosen from vibration and become dislodged if installation parts are not properly tightened. These precautions for the safety of the person who does the panel mounting.

# 2.6 Installation Mounting Clamp



The unit is designed for panel mounting.

1-Insert the unit in the panel cutout from the front side.

2- Insert the mounting clamps to the holes that located top and bottom sides of device and screw up the fixing screws until the unit completely immobile within the panel



Montage of the unit to a system must be done with it's own fixing clamps. Do not do the montage of the device with inappropriate fixing clamps. Be sure that device will not fall while doing the montage.

#### 2.7 Removing from the Panel



Before starting to remove the unit from panel, power off the unit and the related system.



1-Loosen the screws

2-Pull mounting clamps from top and bottom fixing sockets.

3-Pull the unit through the front side of the panel

## **3.Electrical Wirings**



You must ensure that the device is correctly configured for your application. Incorrect configuration could result in damage to the process being controlled, and/or personal injury. It is your responsibility, as the installer, to ensure that the configuration is correct.

Parameters of the device has factory default values. These parameters must be set according to the system's needs.



Only qualified personnel and technicians should work on this equipment. This equipment contains internal circuits with voltage dangerous to human life. There is severe danger for human life in the case of unauthorized intervention.



Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.



Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

#### 3.1 Terminal Layout and Connection Instructions



# 3.2 Electrical Wiring Diagram





Process input is in CAT II class





**Note-1** : There is an internal 33R fusible flame proof resistor in 100-240 V  $\sim$  50/60Hz supply voltage input

There is an internal 4R7  $\,$  fusible flameproof resistor in 24V  $\sim$  50/60Hz , 24V  $_{---}$  supply voltage input

**Note-2**: "L" is (+), "N" is (-) for 24V \_\_\_\_ supply voltage **Note-3** : External fuse is recommended.



Make sure that the power supply voltage is the same indicated on the instrument.

Switch on the power supply only after that all the electrical connections have been completed.

Supply voltage range must be determined in order. While installing the unit, supply voltage range must be controlled and appropriate supply voltage must be applied to the unit. Controlling prevents damages in unit and system and possible accidents as a result of incorrect supply voltage.



There is no power supply switch on the device. So a power supply switch must be added to the supply voltage input. In accordance with the safety regulations, the power supply switch shall bring the identification of the relevant instrument.Power supply switch shall be easily accessible by the user.

Power switch must be two poled for seperating phase and neutral. On/Off condition of power switch is very important in electrical connection. On/Off condition of power switch must be signed for preventing the wrong connection.

If an external fuse is used, it must be on phase connection in  $\sim$  supply input. If an external fuse is used, it must be on (+) line connection in <u>---</u>supply input.



The instrument is protected with an internal fuse (Please refer to Note1 for information). In case of failure it is suggested to return the instrument to the manufacturer for repair.

# **3.5 Process Input Connection**

## 3.5.1 TC (Thermocouple) Connection



Connect the wires with the polarity as shown in the figure left.

Always use compensation wire corresponding to the thermocouple used. If present, the shield must be connected to a proper ground.

(i)

Input resistance is greater than 10M

3.5.2 RTD Connection



I 3-wire Pt-100 connection (with line compensation) (Max. Line impedance is 10)



2-wire Pt-100 connection (without line compensation)

**Note 1 :** In 3-wire system, use always cables of the same diameter (min 1mm<sup>2</sup>) Always use wires of the same gauge and type whether a 2-wire or 3-wire system. **Note 2 :** Install a jumper between terminals 2 and 3 when using a 2-wire RTD.

**Note 3 :** If the distance is longer than 10 meters, use 3-wire system



Input resistance is greater than 10M

# 3.5.3 Process Input Connection of Serial Transmitters with Current Output (Loop Powered)

Transmitter connection by using supply voltage on the device

Transmitter connection by using external supply voltage source.



**Note 1 :** External power supply must be selected according to supply voltage range and required current for transmitter.



# 3.5.4 Process Input Connection of 3-wire Transmitters with Current Output

Transmitter connection by using supply voltage on the device

Transmitter connection by using external supply voltage source.





**Note-1 :** External power supply must be selected according to supply voltage range and required current for transmitter.



## 3.5.5 Connection of Transmitters with Voltage Output to Process Input

Transmitter connection by using supply voltage on the device

l

Transmitter connection by using external supply voltage source.



**Note-1 :** External power supply must be selected according to supply voltage range and required current for transmitter.

Input resistance is greater than 10M for 0...50mV \_\_\_\_ Input resistance is greater than 43K for 0...10V \_\_\_\_

3.6 Galvanic Isolation Test Values of ESM-4930 Process Controller



# 4. Connection Wirings for Outputs in ESM-4930 Process Controller

# 4.1 Process Output (SSR Driver Output) Connection



Fuses must be selected according to the applications.

# 4.2 Alarm Output-1 Relay Connection



Fuses must be selected according to the applications.

# 4.3 Process Output or Alarm Output-2 Relay Connection



Fuses must be selected according to the applications.

#### **5. Definition of Front Panel and Accessing to the Parameters**

#### **5.1 Definition of Front Panel**



Note-1: If increment or decrement button is pressed for 5 seconds continuously, increment and decrement number become 10, if increment or decrement button is pressed for 10 seconds continuously, increment and decrement number become 100.

# 5.2 Observation of Software Revision on the Bottom Display When Power Is On

When the power is applied to the device all led indicators and display segments are momentarily illuminated for testing. Software revision number of the controller is momentarily illuminated on the bottom display.



When power is on, display of the device is like below:



All leds are energised. On bottom display revision number is shown. Revision number is "10".

Main operation screen is shown



(BEWKO)

If there is an unexpected situation while opening the device, power off the device and inform a qualified personnel.

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# 5.3 Adjustment of Process and Alarm Set Values











Note-3: This menu can be observed if <u>DEAF</u> parameter in <u>PEAF</u> section is selected <u>D</u>

Please refer to the Section 6.Parameters for detailed information about Parameters and menus.

# 5.5 Accessing to the Technician Menu

The parameters have been divided into groups according to their functions. Every group has a title and firstly user must determine the title (menu) for accessing to the parameters. Refer to the parameters section for detailed information about parameters.





#### **DiSP List Menu**

It defines which parameter will be shown on top and bottom display

Technician can access to the following menu by pressing menu changing next button

#### **PINP CONF Menu**

Configuration parameters of process input

Technician can access to the following menu by pressing menu changing next button

#### PID CONF Menu

PID algorithm parameters

Technician can access to the following menu by pressing menu changing next button

#### PCnF CONF Menu

Configuration parameters of Process outputs

Technician can access to the following menu by pressing menu changing next button

#### ALn1 CONF Menu

Configuration parameters of ALARM -1 output

Technician can access to the following menu by pressing menu changing next button



By pressing SET button, technician can access to the menu page and all parameters in this menu page.

# 5.6 Changing and Saving Parameters

**Example-1**: To change Process Input Type parameter <u>155L</u>

Process Input Type parameter <u>55L</u> is in "PinP Conf" menu, so PinP ConF menu must be accessed firstly in order to reach <u>55L</u> parameter.







Example-2: Changing operation form from "Auto" to "Manual" and adjustment of % output. If operation form is Auto (Close-Loop Control) and there is an output with PID or ON/OFF control form, device controls the process outputs by calculating the % output values automaticaly.

If operation form is Manual (Open-Loop Control) and there is an output with PID control form, then % output value can be adjusted with increment and decrement buttons.

If operation form is Manual (Open-Loop Control), and there is an output with ON/OFF control form, then %output value can be adjusted "OFF", "HEAT" or "COOL" with decrement and increment buttons.

If operation form is Manual, % output value is shown on bottom display whatever b d 5 P parameter is.

L

Auto/Manual Operation Form can be adjusted Auto or Manual with A/M button from front panel. For using this button, Auto/Manual Operation Type Selection Parameter Prt2 must be no.

For details on this parameter, refer to Section 6.2.8 General Parameters.





Proportional band parameter Pisis in "Pid Conf" menu, so "Pid Conf" menu must be accessed firstly.




#### DiSP List Menu

It defines which parameter will be shown on top and bottom display

Technician can access to the following menu by pressing menu changing

#### **PINP CONF Menu**

Configuration parameters of process input

Technician can access to the following menu by pressing menu changing

#### PID CONF Menu

PID algorithm parameters

Enter Set button to access to Pid ConF menu

**Proportional Band** 

Parameter can be changed with increment and decrement buttons

**Proportional Band** 

Press Set button to confirm the value and access to the next parameter



**Example-4** : To change \_\_\_\_Voltage / Current Input Calibration Type Selection parameter <u>u[RL]</u> In "PinP Conf" menu

 $\square$  Parameter is in "PInP ConF" menu. For accessing to this parameter, technician must access to "PInP ConF" menu firstly. In this example, changing input type of a device from thermocouple to  $\_\_\_$ Voltage/Current and dual point calibration selection is shown.





#### **DiSP List Menu**

It defines which parameter will be shown on top and bottom display

Technician can access to the following menu by pressing menu changing next button

#### **PINP CONF Menu**

Configuration parameters of process input

Enter PinP ConF menu by pressing Set button

# Process Input Type Selection

For accessing to <u>LAL</u> parameter, <u>551</u> parameter must be <u>2</u>. If it is not <u>2</u>, change the value as <u>2</u> With increment button.

Press Set button to confirm the value and access to the next parameter

#### ----Voltage / Current Input Type Selection

Press Set button to access to the next parameter

#### **Decimal Point Position**

Press Set button to access to the next parameter



#### 6. Parameters

Parameters are divided into two groups. They are Process / Alarm Set parameters and Technician parameters. Technician parameters are grouped into subgroups according to their functions. The subgroups are named as menu pages.

### 6.1 Process / Alarm SET Parameters

PSEE Process set value
 PSEE Process set value can be adjusted from minimum value of set scale 5U - L to maximum value of set scale 5U - L
 Set value for alarm output-1
 AL - Process set value can be adjusted from minimum value of set scale 5U - L to maximum value of set scale 5U - L
 Set value for alarm output-2. It is accessible if D - F parameter is
 BL - Process set value can be adjusted from minimum value of set scale 5U - L to maximum value of set scale 5U - L



For changing Alarm Output-1 and Alarm Output-2 Set values, Alarm Set Values protection parameter Prbl i must be no

### 6.2 Technician Parameters

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#### **TUNE SELECTION**

By selecting one of the methods below, device can determine the PID parameters.



Device operates according to the defined PID parameters



Auto tune (Limit Cycle Tuning) operation

Self tune (Step Response Tuning) operation



RESE

Auto-Self Tune

Self Tune operation is performed, if the conditions are realized when power on firstly. In normal operation, it controls the tune conditions in **Auto Tune** selection which explained below. If any of the conditions is realized, it performs the **Auto Tune** operation.

# 



Device does not do  $\underline{R} \underline{L} \underline{\Box} \underline{\Box}$  (Limit Cycle Tuning) operation or while  $\underline{R} \underline{L} \underline{\Box} \underline{\Box}$  operation runs, this selection is adjusted  $\underline{\Box} \underline{\Box} \underline{\Box}$  and **Auto Tune** operation is canceled.



If <u>Lunn</u> parameter is <u>RLun</u> or <u>RL5E</u>, when the conditions for Auto Tune parameter that are explained in Tune Methods section are realized, it starts to perform Auto Tune (Limit Cycle Tuning) operation.



By pressing AT button, Automatic Tune can be selected 9E5 or noFor being able to use AT button, AT (Auto Tune) Button protection parameter PrE3 Must be no. (For details, refer to Section 6.2.8 General Parameters)

#### **TUNE METHODS**

There are 2 different methods for determining PID parameters by the device. These are **Auto tune** (Limit Cycle Tuning) and **Self Tune** (Step Response Tuning) methods.

Determining of PID parameters with **Auto Tune** is started in these conditions : **1-** By the user in any time,

2-By the device when system gets unstable and starts oscillation

If process value is out of **Set \pm Process value stabilisation**  $5 \pm rn$  value (Please refer to Section 6.2.4) and starts to oscillates, then device changes the

 $B \vdash E \cap$  Parameter to  $\Box \subseteq E \subseteq$  and Auto Tune operation is started.

**3-** After changing set value, if difference between newly defined set value and former set value is greater than proportional band, device will start it.

If set value is changed to a value that is greater than;

±[Scale \* (Heating or Cooling Proportional Band)]/1000 value,

REEN Parameter is adjusted <u>YES</u> by the device and **Auto Tune** operation is started.

#### Example -1 : Starting Auto Tune operation by the user ;

- Enter technician menu.
- Adjust tune selection parameter <u>Lunn</u> in "run List" menu, **Auto Tune** <u>RLun</u> or **Auto-Self Tune** <u>RL5E</u>
- Adjust automatic tune selection parameter REEn in "run List" menu YES And return to main operation screen.
- Observe that "AT" led is active.

If **Auto Tune** operation finishes without any problem, device saves the PID coefficients to memory and continue to run.  $\boxed{\texttt{R}\texttt{L}\texttt{L}\texttt{n}}$  Parameter is adjusted  $\boxed{\texttt{n}\texttt{o}}$  automatically.

Canceling **Auto Tune** operation:

1- If sensor breaks;

l

2- If Auto Tune operation can not be completed in 8 hours

3-If user adjusts Eurn parameter no or Stun

4- If user adjusts ALL n parameter no

5- If process set value is changed while Tune operation is being performed

**6-** While Tune operation is being performed, if operation type selection is changed as "Manual" when it is "Automatic" (If operation type selection is changed as "Automatic" when it is "Manual", then Tune operation is started again)

**7-** If output function is changed while Tune operation is being performed (Heat Cool, Cool Heat)

8- While Tune operation is being performed, if control form is changed as "ON/OFF" when it is "PID" (If control form is changed as "PID" when it is "ON/OFF", the Tune operation is started again)

Auto Tune is canceled. Then, without doing any changes in PID parameters and  $\boxed{B \vdash L \cap}$  Parameter, device continues to run with former PID parameters.

# For Auto Tune (Limit Cycle Tuning) operation :

1- Tune slection parameter <u>Lunn</u> in "run List" menu must be selected <u>RLun</u> Auto tune or <u>RLSE</u> Auto-Self tune.

**2** - For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD or PID.

Auto Tune (Limit Cycle Tuning) operation ;

if heating or heating-cooling function and PID control form is selected, process control output runs according to heating

if cooling function and PID control form is selected, process control output runs according to cooling.



#### Self Tune (Step Response Tuning):

When power is on, while process value starts to change for being equal to process set value, PID parameters are determined by the device with **Self Tune** method.

For starting **Self Tune (Step Response Tuning )** operation firstly power off and then apply power to the device. Also difference between process value and set value must be too much.

#### Example 2 : Determination of PID parameters with Self Tune method

- Enter technician menu
- Select tune selection parameter <u>Lunn</u> in "run List" menu <u>Stun</u> or <u>RLSE</u> and turn to operation screen.
- Power off the device.
- Wait system to be in first conditions.
   (For example : Decrease of the temperature to ambient temperature while controlling the temperature)
- Apply power to the device
- See that "AT" led is active

If heating or heating-cooling function and PID control form is selected for the system;

If set value is greater than process value, process output becomes active till to the **Temperature+[(Set - Temperature) / 2]** value. When process value reaches to this value, process output reduces to 0% and it calculates the PID coefficients.



#### For Self Tune (Step Response Tuning) operation :

1-Tune selection parameter <u>Lunn</u> in "run List" menu must be selected **Self tune** <u>SEun</u> Or **Auto-Self Tune** <u>RESE</u>

2 - For **Self Tune (Step Response Tuning)** operation, firstly power off and then apply power to the device.

**3** - For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD or PID.



If cooling function and PID control form is selected for the system;

If set value is less than process value, process output becomes active till to the **Temperature - [( Temperature - Set ) / 2]** value. When process value reaches to this value, process output is reduced to 0% and it calculates PID coefficients.





#### For Self Tune (Step Response Tuning) operation :

1 - Tune selection parameter <u>Lunn</u> in "run List" menu must be selected **Self tune** <u>5 Lun</u> Or **Auto-Self Tune** <u>RE5</u>

2 - For **Self Tune (Step Response Tuning)** operation, firstly power off and then apply power to the device.

**3** - For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD or PID.

If **Self Tune** operation is finished without any problem, device saves new PID parameters to memory and runs. It changes <u>Lunn</u> parameter.

If <u>Lunn</u> parameter is <u>5Lun</u> it is changed to <u>no</u>, if it is <u>RESE</u>, it is changed to <u>RLun</u>

If **Self Tune** operation is interrupted at half, PID parameters and  $\lfloor unn$  parameter are not changed, device continues to run with former PID parameters. When power is off and then on, device starts to complete the **Self Tune** operation.

Canceling Self Tune operation :

1-If sensor breaks;

2- If Self Tune operation can not be completed in 8 hours;

**3-** While heating **Self Tune** operation is running, if process value becomes greater than Set value ;

**4-** While cooling **Self Tune** operation is running, if process value becomes less than Set value ;

5- If user selects Lunn parameter no or ALun

6- If process set value is changed while Tune operation is being performed

7- While Tune operation is being performed, if operation type selection is changed as "Manual" when it is "Automatic"

**8-** If output function is changed while Tune operation is being performed (Heat Cool, Cool Heat)

**9-** While Tune operation is being performed, if control form is changed as "ON/OFF" when it is "PID" (If control form is changed as "PID" when it is "ON/OFF", the Tune operation is started again)

**Self Tune** operation is canceled. Then device continues to run with former PID parameters without changing PID parameters.



#### For Self Tune (Step Response Tuning) operation :

1 - Tune selection parameter <u>Lunn</u> in "run List" menu must be selected **Self tune** <u>Stun</u> Or **Auto-Self Tune** <u>RESE</u>

2 - For **Self Tune (Step Response Tuning )** operation, firstly power off and then apply power to the device.

**3** - For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD or PID.



# **BUMPLESS TRANSFER**

П	ſ

Process output value in manual control is not taken into consideration while passing from manual control to automatic control. New control output that is measured in automatic control is applied to process output.

Last %output value is taken output value of manual control and manual control continues while passing from automatic control to manual control.



While passing from manual control to automatic control, last process output value in manual control is accepted as first process output value in automatic control and automatic control continues to run.

Last % process output value in automatic control is accepted as process output value of manual control and manual control continues to run.

# 

Alarm latch canceling is not performed.



If there is an alarm output with latching and there is no alarm status, latching operation will be finished by the device. When it is finished, this parameter becomes Automatically.



















If 0 - db > 0





#### SENSOR BREAK OUTPUT VALUE 5600 (FOR HEATING PID 0.0%, 100.0%) (FOR COOLING PID -100.0%, 0.0%)

When sensor breaks, controlling of the process can continue by entering % output value to 5bou parameter.

If this parameter 0.0, process control output does not perform an output when sensor breaks.

# 5588

# Soft Start Set value

It can be adjusted from 0 to 9999 with increment and decrement buttons. If parameter is selected \_\_\_\_\_, Soft start function becomes inactive. When the device power on, if the Soft start set value different from \_\_\_\_and temperature value is lower than soft start value on heating processes, device starts soft start operation, until temperature reaches soft start set value. On soft start device output period is SSCt parameter value and device control output is SSCo parameter value.



# **Soft Start Control Output**

It can be adjusted from 10% to 90% with increment and decrement buttons.

# SSEE

#### Soft Start Control Period

It can be adjusted from 1 to 100 sec with increment and decrement buttons.

ΡΓοΡ	6.2.5 Proc	ess Output Configuration Parameters
Eonf		It determines if Process Output (SSR Driver Output) and Alarm Output-2 operates together or not.
		Process Output (SSR Driver Output) and Alarm Output-2 operates separately.
		Process Output (SSR Driver Output) and Alarm Output-2 operates together. Alarm functions of Alarm Output-2 can not be used
	oFn[	It determines output functions of Process Outputs
		HERE Heating
	[ЕЧР	It determines control algorithms of Process Outputs
		ON/OFF control algorithm
		P, d PID control algorithm
<u>[</u> <u>E</u> <u>y</u> P onoF	► ₩¥\$	Hysteresis value of Process Outputs. It can be adjusted from 0% to 50% of full scale. (It is active if ON/OFF control is selected)
	►₩₽∩	It determines operation form of hysteresis (It is active if ON/OFF control is selected)
		SV+HYS/2 and SV-HYS/2
		SV and SV+HYS or SV and SV-HYS
	►oFFŁ	In ON/OFF operation, this time must be passed for the output to be energised again. It can be adjusted from 0.0 to 100.0 seconds. (It is active if ON/OFF control is selected)



# **Process high alarm**



# Process low alarm



#### **Deviation high alarm**



# **Deviation low alarm**



# **Deviation band alarm**



Process Value

#### **Deviation range alarm**



Alarm- 1 hysteresis value.

it can be adjusted from 0% to 50% of process input scale  $(\_\_PL] - \_L\_DL$ ) It is active if logic output function of Alarm Output-1 is alarm output.

Alarm on delay time for Alarm Output-1. It can be adjusted from 0 to 9999 seconds. It is active if logic output function of Alarm Output-1 is alarm output.

Alarm off delay time for Alarm Output-1. It can be adjusted from 0 to 9998 seconds. When the value is greater than 9998, <u>L E H</u> is seen on the screen. It means alarm latching output is selected. It is active if logic output function of Alarm Output-1 is alarm output.



Lou

0

Ron

Alarm stabilisation time for Alarm Output-1. It can be adjusted from 0 to 99 second. It is active if logic output function of Alarm Output-1 is alarm output. After the unit is power-on and Alarm Stabilisation Time is expired, if an alarm condition which is selected with Alt1 is present, then Alarm output-1 becomes active.







#### Process low alarm



**Deviation high alarm** 



# **Deviation low alarm**



# **Deviation band alarm**



# Deviation range alarm



Alarm-2 hysteresis value.

8L X Z

Loud

0

it can be adjusted from 0% to 50% of process input scale  $( \_\_\_P\_] - \_\_\_\_\_\_]$  ) It is active if logic output function of Alarm Output-2 is alarm output.

Alarm on delay time for Alarm Output-2. It can be adjusted from 0 to 9999 seconds. It is active if logic output function of Alarm Output-2 is alarm output.

Alarm off delay time for Alarm Output-2. It can be adjusted from 0 to 9998 seconds. When the value is greater than 9998, <u>L E L H</u> is seen on the screen. It means alarm latching output is selected. It is active if logic output function of Alarm Output-2 is alarm output.



Alarm stabilisation time for Alarm Output-2. It can be adjusted from 0 to 99 second. It is active if logic output function of Alarm Output-2 is alarm output. After the unit is power-on and Alarm Stabilisation Time is expired, if an alarm condition which is selected with Alt2 is present, then Alarm output-2 becomes active.



"Aln2 Conf" Menu is accessible if a C r F parameter in "PCnF ConF" is

#### 6.2.8 General Parameters



# Image: Constraint of the second state of the second



**LCPS** It is used for accessing to the technician parameters. It can be adjusted from 0 to 9999.

If it is \_\_\_\_\_\_ ; there is no password protection while entering to the technician parameters.

# If it is different from "0" and user wants to access to the technician parameters;

1-If technician does not enter ECPS password correctly:

It turns to operation screen without entering to operator parameters.

**2-**When <u>ECPS</u> in top display and <u>D</u> in bottom display, if technician presses SET button without entering <u>ECPS</u> password (For observing parameter)

Technician can see all menus and parameters except Technician Password menu ("Pass Conf"), but parameters can not be changed. (Please refer to Section 7. Failure Messages (4) in ESM-4930 Process Controllers)

### 7. Failure Messages in ESM-4930 Process Controllers



**1** - Sensor failure in analogue inputs. Sensor connection is wrong or there is no sensor connection.



**2** - If value on top display blinks : If analogue input value is less than minimum value of operating scale  $\boxed{LoL}$  value on the top display starts to blink.

In "PinP Conf" Menu if; 155L = 0; E5L = 2; un E = 0; LoL = 200; uPL = 900 are defined. Adjust LoL = 150

If analogue input value is less than minimum value of operating scale  $\boxed{L \Box L}$  Value on the top display starts to blink.



Please refer to Section 6.2.3 for detailed information about this parameter.



**3** - If value on top display blinks : If analogue input value is greater than maximum value of operating scale  $\boxed{uPL}$  top display starts to blink.

In "PinP Conf" Menu if;	
<u>.55L</u> = <u>D</u> ; <u>ECSL</u> = [	2; unit = 0;
Lol = -200; UPL = (	900 are defined
Adjust uPL 850	

If analogue input value is greater than maximum value of operating scale  $\Box PL$  value on the top display starts to blink.



Please refer to Section 6.2.3 for detailed information about this parameter.



**4** - If technician password is different from "0" and technician accesses to the parameters by Set button without entering the technician password and wants to change a parameter, device does not allow to do any changes in parameters. If increment or decrement button is pressed, a warning message will appear on the bottom display as shown on the left.



**5** - If tuning operation can not be completed in 8 hours, AT led starts to blink.Blinking can be canceled by pressing Enter button.

For details on parameters, refer to Section 6.2.1



**6** - If user does not do anything for 120 seconds while device is on technician menus, device turns to operation screen.



8. Specifications	
Device Type	: Process Controller
Housing&Mounting	: 96mm x 48mm x 86.5mm 1/8 DIN 43700 plastic
	housing for panel mounting. Panel cut-out is 92x46mm.
	Type-1 Enclosure Mounting.
Protection Class	: NEMA 4X (IP65 at front, IP20 at rear).
Weight	: Approximately 0.21 Kg.
Environmental Ratings	: Standard, indoor at an altitude of less than 2000 meters with none condensing humidity.
Storage/Operating Temperature	e : -40 °C to +85 °C / 0 °C to +50 °C
Storage/Operating Humidity	: 90 % max. (None condensing)
Installation	: Fixed installation
Over Voltage Category	: 11
Pollution Degree	: II, office or workplace, none conductive pollution
Operating Conditions	: Continuous
Supply Voltage and Power	: 100 - 240 V~ (-15% / +10%) 50/60 Hz  6VA
	24 V~ (-15% / +10%) 50/60 Hz 6VA
	24 V (-15% / +10%) 6W
Process Inputs	: Universal input TC, RTD, Voltage/Current
Thermocouple Input Types	: Selectable by parameters
	L (DIN43710),
	J ,K ,R ,S ,T ,B ,E ,N (IEC584.1)(ITS90) , C (ITS90)
Thermoresistance Input Types	: PT 100 (IEC751) (ITS90)
Voltage Input Types	: Selectable by parameters 050mV , 05V,
	010V
Current Input Types	: Selectable by parameters 020mA , 420mA

Accuracy	: ± 0,25% of full scale for thermocouple, thermoresistance and <u></u> voltage ± 0,70% of full scale for current.
Cold Junction Compensation	: Automatically ± 0.1°C/1°C.
Line Compensation	: Maximum 10 .
Sensor Break Protection	: Upscale
Sampling Cycle	: 3 samples per second
Input Filter	: 0.0 to 900.0 seconds
Control Forms	: Programmable ON / OFF, P, PI, PD or PID.
Relay Outputs	: 2 pieces 5A@250V~ (at resistive load) (Programmable control or alarm output) (Electrical Life :100000 operation (Full Load))
Standard SSR Driver Output	: Max. 17mA, Max. 25V
Process Display	: 13.2 mm Red 4 digit LED display
Set Display	: 8 mm Green 4 digit LED display
Led Indicators	: AT (Auto Tune), M (Manual Mode), A (Automatic Mode), PSET (Process Set value), ASET1 (Alarm-1Set value), ASET2 (Alarm-2 Set value), PO (Process Output), AO1 (Alarm Output-1), AO2 (Alarm Output-2) °C / °F / V unit leds
Approvals	: UL Recognized Component (File No : E 254103), [fil], C €

#### 9. Other Informations

#### Manufacturer Information:

Emko Elektronik Sanayi ve Ticaret A.Ş. Demirtaş Organize Sanayi Bölgesi Karanfil Sk. No:6 16369 BURSA/TURKEY

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